

Analysis of Research Method, Results and Regulations Regarding the Exhaust Emissions from Two-Wheeled Vehicles under Actual Operating Conditions

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ABSTRACT

The subject of this article was the analysis of the current state of legislation regarding the exhaust emissions from two-wheeled vehicles. The regulations and emission limits were analyzed and compared for different areas of the world. Moreover, the review of the legal provisions includes an individual approach to specific categories of two-wheeled vehicles. The study also describes the research and exhaust emission measurement methods from mopeds and motorcycles both under laboratory conditions and in actual operation. The methods were evaluated in the aspect of future emission requirements and trends. In addition, the results of emissivity measurements under actual operating conditions obtained in the Poznań agglomeration with the use of motorcycle units were discussed and analyzed. The values of road emissions of all toxic compounds limited by legislators were compared with emission standards.

Keywords: air pollution, two-wheeled vehicles, exhaust emission, RDE methodology, PEMS.

INTRODUCTION

In 1942, the smog phenomenon was first identified in California. A decade later, it was discovered that it was formed as a result of the emissions of nitrogen oxides and unburned hydrocarbons, to which transport also contributed. In 1966, a law was introduced there to control the car emissions. Over the next few years, the Environmental Protection Agency was established, which introduced the first limits. The Agency's activities led to the spread of catalytic converters, sensors measuring the oxygen content and the introduction of unleaded gasoline. In Europe, two-wheelers belong to the L category vehicles. The first provisions regarding their emission were brought about in 1972 by Directive 72/306/EEC [European Union 2005] and Regulation 24, with the provisions regarding two-wheelers only contained in the regulations, while the Directive

deals with four-wheeled vehicles. Currently, the European Union regulates the emission of carbon monoxide, hydrocarbons and nitrogen oxides for two-wheelers. The current European standard for two-wheelers is the EURO 4 norm. In the two-wheelers with a displacement of over 125 cm³, the ABS system has become mandatory and an integrated vehicle braking systems for the engines with smaller displacement. Another change brought by this standard is the abandonment of carburetor systems in favor of electronic carburetors and injectors. Catalytic systems are equipped with lambda probes. The perceptible advantage of the current legislation for the vehicle user is the reduction of the fuel consumption and improvement in the level of reliability of two-wheelers with smaller displacement engines, due to the replacement of some mechanical systems, often requiring adjustment, with electronic ones. The upcoming change on the European vehicle

market is the EURO 5 norm, which is expected to enter into force in 2020. It not only provides a reduction in the maximum permitted emission of toxic compounds, but also an increase in the number of diagnostic points in the engine, especially in the exhaust aftertreatment system. In recent years, there has been a growing emphasis on the research conducted under actual traffic conditions. Higher emissions of nitrogen oxides under actual traffic conditions was found, in addition to frequent significant discrepancy in fuel consumption between the information contained in the vehicle technical data sheet and the values observed during everyday operation, which was already pointed out by scientists and vehicle users themselves [Hiesmayr et al. 2017; Kumar et al. 2011; Tong, Hung and Cheung 2000].

LEGAL ASPECTS OF TWO-WHEELED VEHICLE EMISSIONS

As a result of Directive 2007/46/EC [European Union 2007], an L type approval category was established, which included the bikes equipped with an engine, two- and three-wheel mopeds, motorcycles, motorcycles with side-car, three-wheeled vehicles, microcars, four-wheel off-road vehicles and four-wheeled vehicles. Separate emission norms are set by the European Union, the United States and California, as well as Brazil, Chile, China, India, Indonesia, Japan, Singapore, South Korea, Thailand and Vietnam. Some of these countries model their norms on the EURO standards, introducing them a few years after their introduction in Europe. The current standard on the European market for two-wheelers is the EURO 4 standard, while the EURO 5 standard will come into force in 2020 (Table 1).

The American motorbike emission norms have been setting maximum emission values since 1980: HC 5 g/km, CO 12 g/km. The data was collected using the FTP-75 test. For the vehicles manufactured up to and including the year 2005, no exhaust fumes emission norms have been set. The California norms (since 2004) and federal norms (since 2006), specify the average hydrocarbon emissions for a given manufacturer. Unlike European norms, they do not distinguish between different types of fuel.

Currently, the toxic exhaust emissions of two-wheeled vehicles are tested using a chassis dynamometer and adopted type approval tests. Each test determines the masses of carbon monoxide, hydrocarbons, nitrogen oxide, carbon dioxide and fuel consumed during the measurement cycle. The dust mass is determined for certain categories. The ECE R40 (*European Emission Test Cycle*) lasts 1170 seconds and consists of six basic urban cycles (Fig. 1). Each of those cycles consists of fifteen phases reflecting the aspects of actual driving conditions. The ECE R47 test cycle lasts 896 seconds and consists of eight basic cycles (Fig. 2), which must be carried out without interruption, and the measurement is made throughout the entire driving cycle, from the moment the engine is started.

Each of the cycles consists of seven phases, reflecting the driving conditions. For the vehicles of the L1e-A and L1e-B categories with a maximum expected speed of 25 km/h, the cut-off speed chart applies. In turn, the WMTC (*World Motorcycle Test Cycle*) test cycle lasts 1800 seconds and consists of three parts (Fig. 3). As with ECE R40 and ECE R47 cycles, they should be performed without interruption. The WMTC test will apply to all two-wheeled vehicles with the entry into force of the EURO 5 standard in 2020.

Table 1. Limit values for toxic compounds emission in the EURO 5 norm [Delphi 2017]

| EURO 5 STEP | | | | | | | | |
|------------------|-------------------------------|------------------|-----------------|-----------------|-----------------|-----------------|----------------|------------|
| Vehicle Category | Vehicle Category Name | Propulsion Class | Mass of [mg/km] | | | | | Test Cycle |
| | | | CO | THC | NHMC | NO _x | PM | |
| | | | L ₁ | L _{2A} | L _{2B} | L ₃ | L ₄ | |
| L1e-A | Powered cycle | PI/CI/Hybrid | 500 | 100 | 68 | 60 | 4,5 | WMTC |
| L1e-B-L7e | All other L-category vehicles | PI/PI/Hybrid | 1000 | 100 | 68 | 60 | 4,5 | WMTC |
| | | CI/CI/Hybrid | 500 | 100 | 68 | 90 | 4,5 | WMTC |

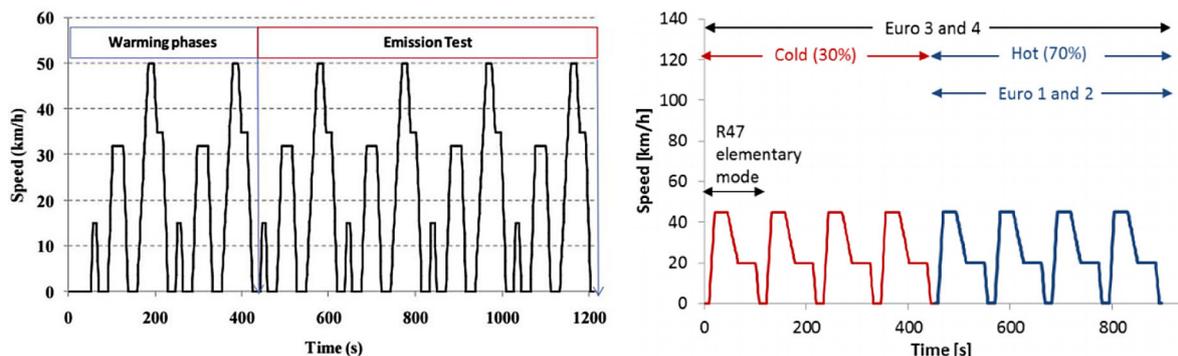


Fig. 1. Characteristics of tests a) ECE R40 [Khanh, Han and Vinh 2018] b) ECE R47 [Giechaskiel, Zardini and Martini 2015]

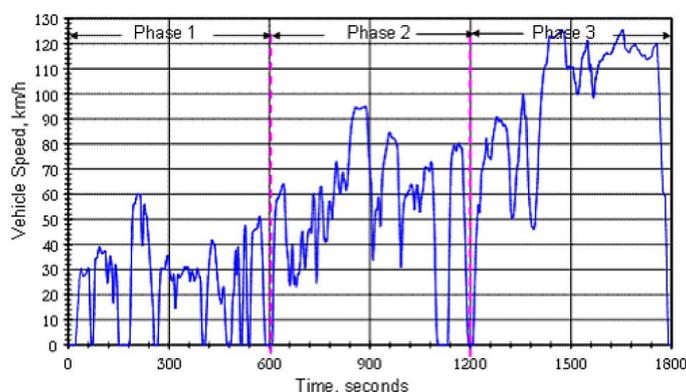


Fig. 2. Characteristics of a WMTC test [asphaltandrubber.com 2019]

RDE TESTS – OVERVIEW

It was noticed that results of the test conducted under laboratory conditions deviate significantly from the test results under actual traffic conditions, especially in terms of load variability, which affects the work of exhaust aftertreatment systems and the exhaust emissions of harmful components, especially carbon monoxide. [Fuć et al. 2004].

From September 1, 2017, new car models are subject to RDE (*Real Driving Emissions*) and WLTP (*World Harmonized Light Vehicle Test Procedure*) tests. Non-compliance to the limit values determined on the basis of valid type approval tests and values obtained under actual operating conditions was also found for other road and off-road vehicles, including motorcycles and mopeds. This incompatibility has been well documented and is the subject of this article.

In the RDE test, supplementing laboratory tests, the vehicle moves under actual operating conditions, according to randomly selected parameters [Pielecha 2017]. It provides complete

and very accurate monitoring of pollutants emitted by engines in real time, along with the related engine, vehicle and environment parameters. The measurement is carried out using portable emission measurement systems (PEMS) that are mounted on the vehicle (Fig. 3).

In the case of passenger cars, it lasts between 90 and 120 minutes and consists of three sections: urban (speed of up to 60 km/h, 34% of distance), rural (speed 60–90 km/h, 33% of distance) and highway (speed over 90 km/h, 33% of the distance), with an accuracy of ± 10 percent points for the distances, with at least 29% being an urban part. The maximum duration of one-time stop of the vehicle is 180 s. The ambient temperature should be between 0°C and 30°C (the extended range lowers the minimum to -7°C , and increases the maximum to 35°C). Topographic altitude should be at most 700 m a.s.l. (extended range increases that to: $700 < h \leq 1300$ m a.s.l.), and a total height increase of less than 1200 m/100 km. The RDE tests are carried out on working days on paved roads and streets. The measuring equipment should be installed with particular focus on

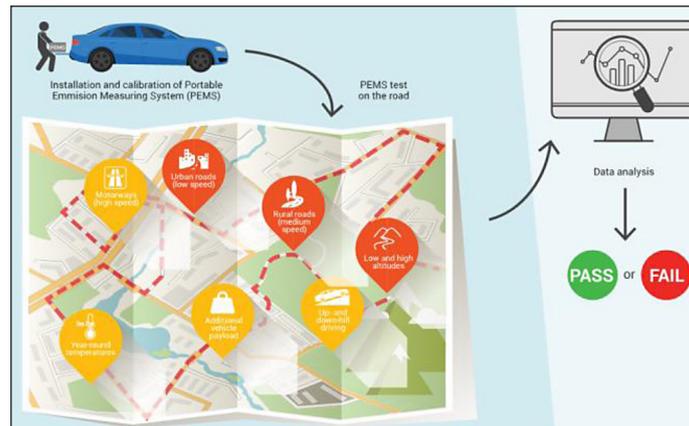


Fig. 3. RDE testing method [caremissiontestingfacts.eu 2019]

causing the smallest possible impact on the exhaust emissions of the vehicle and its operation, as well as on the smallest possible impact on the weight and aerodynamics of the vehicle itself.

The Institute of Internal Combustion Engines and Transport at the Poznań University of Technology specializes in testing the toxic exhaust emissions under actual operating conditions from vehicles of various categories, which has been described, among others in [Merkisz et al. 2014; Merkisz et al. 2012].

RESEARCH METHOD

Research objects

For the emissivity conducted tests under actual operating conditions, two two-wheeled vehicles belonging to the category L3e were used. The first one was a motorcycle, equipped with a four-stroke engine with a displacement of 125 cm³ and a power of 9 kW (Fig. 4a). In addition, the vehicle was equipped with a three-way catalytic

converter and a start-stop system (the start-stop system was inactive during the performed tests). Its technical data is presented in Table 2. The second research object represented a four-stroke motorcycle with a displacement of 847 cm³ and a power of 84.5 kW (Fig. 4b). Its wider specification is presented in Table 3. Both vehicles were manufactured in 2017, and so they were approved with the current EURO 4 standard. Before the tests, the vehicles were checked for possible defects, and both drives were performed by the same driver to avoid the impact change of driving style on the final results.

TEST ROUTE

The tests under actual operating conditions were carried out in the city center of Poznań. It was selected based on the specific road conditions, containing a sufficiently large number of intersections, traffic lights and vehicle speed limits (particularly important in the case the first vehicle test drive). The route was 7.1 km long, and its



Fig. 4. Tested vehicles with the measuring equipment installed

Table 2. Test vehicle technical data

| | |
|---|---------------------------|
| Engine type | 4 stroke |
| Number and arrangement of cylinders, number of valves | single-cylinder, 2 valves |
| Displacement | 125 cm ³ |
| Bore/stroke | 52.4 mm / 57.9 mm |
| Maximum power | 9.0 kW/8500 rpm |
| Maximum torque | 11.8 Nm/5000 rpm |
| Cooling | liquid |

Table 3. Test vehicle technical data

| | |
|---|----------------------|
| Engine type | 4-stroke, DOHC |
| Number and arrangement of cylinders, number of valves | 3-cylinder, 4 valves |
| Displacement | 847 cm ³ |
| Bore/stroke | 78 mm / 59.1 mm |
| Maximum power | 84.6 kW/10000 rpm |
| Maximum torque | 87.5 Nm/8500 rpm |
| Cooling | liquid |

beginning took place at the Poznan University of Technology at the laboratory of the Institute of Internal Combustion Engines and Transport, which greatly facilitated the research process. Both tests were carried out in the afternoon so that the driving conditions were as similar as possible. The test route (Fig. 5) was created on the basis of the data from the GPS system and the GPSvisualizer program.

same measuring apparatus so that the results were as comparable as possible. The AXION R/S+ device, belonging to the PEMS (*Portable Emission Measurement System*) group, was used for this research. The apparatus measures the emission of harmful and toxic compounds, both gaseous: hydrocarbons (HC), carbon monoxide (CO), carbon dioxide (CO₂), nitrogen oxide (NO) as well as solid particles. The specification of the device is shown in Table 4, while the apparatus itself is shown in Figure 6. Electrochemical analyzers are used to determine the emissions of NO and O₂. The concentrations of hydrocarbons, carbon monoxide, and carbon dioxide are measured using a non-dispersion

MEASURING EQUIPMENT

The exhaust emission tests from two-wheeled vehicles under actual operating conditions were carried out in both cases using the

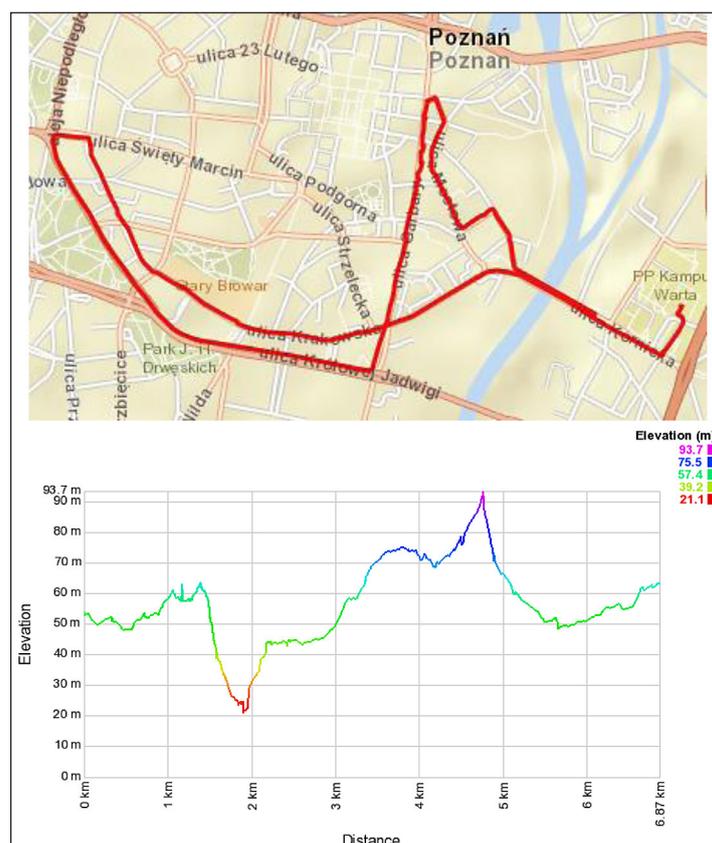


Fig. 5. The test route [gpsvisualizer.com 2019]

Table 4. The AxionR/S+ device operating parameters [globalmrv.com 2019]

| Gas | Mesaurement range | Accuracy | Resolution | Type of mesaurement |
|-----------------|--|-----------------------------|------------------------|---------------------|
| HC | 0–4000 ppm | ± 8 ppm abs. or ±3% rel. | 1 ppm | NDIR |
| CO | 0–10% | ± 0.02% abs. or ±3% rel. | 0.001 vol. % | NDIR |
| CO ₂ | 0–16% | ± 0.3% abs. or ±4% rel. | 0.01 vol. % | NDIR |
| NO | 0–4000 ppm | ± 25 ppm abs. or ±3% rel. | 1 ppm | E-chem |
| O ₂ | 0–25% | ± 0.1% ppm abs. or ±3% rel. | 0.01 vol. % | E-chem |
| PM | 0 mg/m ³ to 300 mg/m ³ | ± 2% | 0.01 mg/m ³ | Laser Scatter |

**Fig. 6.** The measuring equipment used

infrared analyzer – NDIR (*Nondispersive Infra-red Sensor*). In turn, a method based on *Laser Scatter* is used for measuring the PM emission.

Moreover, the device is equipped with a weather station, a GPS and a module for recording the data from the OBD (*On-Board Diagnostic*) vehicle diagnostic system. The data measurement and acquisition was carried out at a frequency of 1 Hz. On the basis of the recorded data, corrections of the obtained results are made, and then the road/specific emission of the tested exhaust gases was calculated.

The device is one of the most modern measuring instruments, housing analyzers for measuring both gaseous and solid compounds in a housing weighing only 18 kg. Low weight and dimensions mean that it can be used to test the emission of all toxic compounds limited by standards from two-wheeled vehicles under actual operating conditions. In addition, the device also measures the particulate matter emissions, the limit on which is expected to enter into effect in 2020 along with the introduction of the EURO 5 norm.

ANALYSIS AND RESULTS

The tests carried out under actual operating conditions allowed plotting comparative characteristics of vehicle speed curves and the exhaust emission intensity in real time during the measurements. For both drives, the highest recorded speed is about 70 km/h, which probably resulted from a temporary change in the terrain, i.e. “coasting”. Significant differences in the emission values of all toxic compounds are noticeable, which is undoubtedly related to the different technical parameters of the engines of the tested vehicles. This fact confirms that for typical urban conditions (numerous stops, speeds of up to 50 km/h) smaller motorcycles with smaller engine displacement will be more environmentally favorable, such as with engines up to 250 cm³ and mopeds (Fig. 7–9). Only in the case of nitrogen oxides emissions, the opposite is the case, which is associated with higher loads in the engines with lower maximum power (Fig. 10). In the case of a motorcycle with a larger engine, the urban drive cycle should be treated only as part of the whole research test, while for mopeds and small motorcycles (colloquially called scooters) this cycle by itself is sufficient to develop the RDE methodology.

Moreover, the measurement data obtained while driving in urban traffic allowed plotting the characteristics of the time density for each of the tested two-wheeled vehicles; thus, a graphical representation of the share of operating time in individual speed and acceleration intervals was prepared. The relations obtained showed that both vehicles most often worked in the interval of 0 km/h speed and acceleration in the range (-0.5–0 m/s²), i.e. at idle. The operating time share in this interval was 34% and 32%, for a motorcycle with a displacement of 125 cm³ and 900 cm³, respectively (Fig. 11). This is related to the characteristics of urban traffic, which includes the phenomenon of road congestion or frequent intersections with traffic lights.

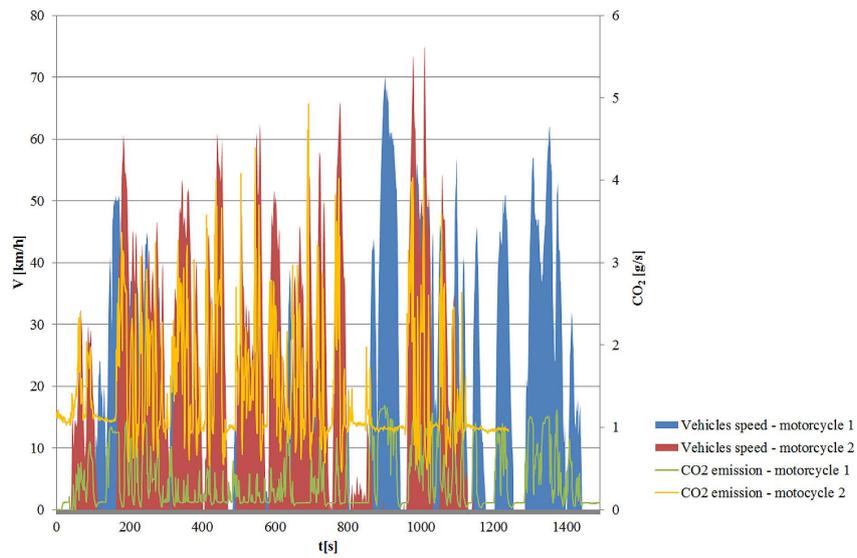


Fig. 7. The CO₂ emission characteristics and vehicle speed presented in time

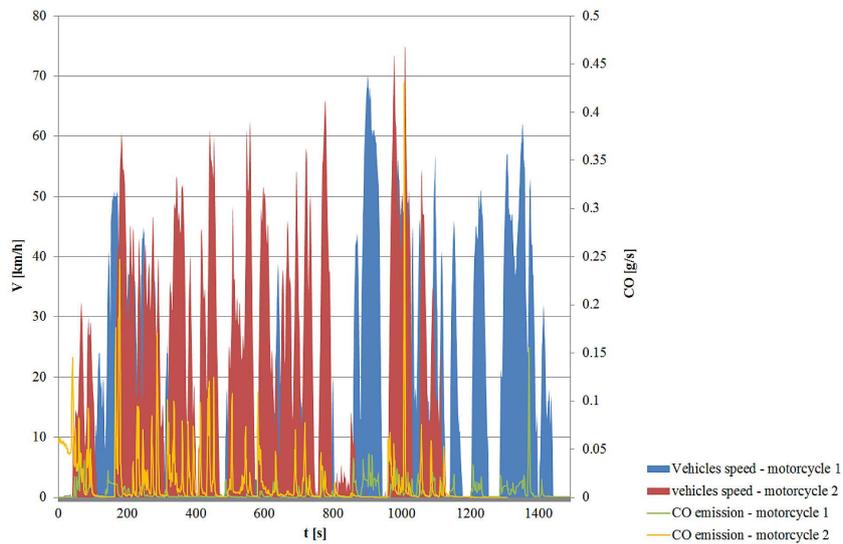


Fig. 8. The CO emission characteristics and vehicle speed presented in time

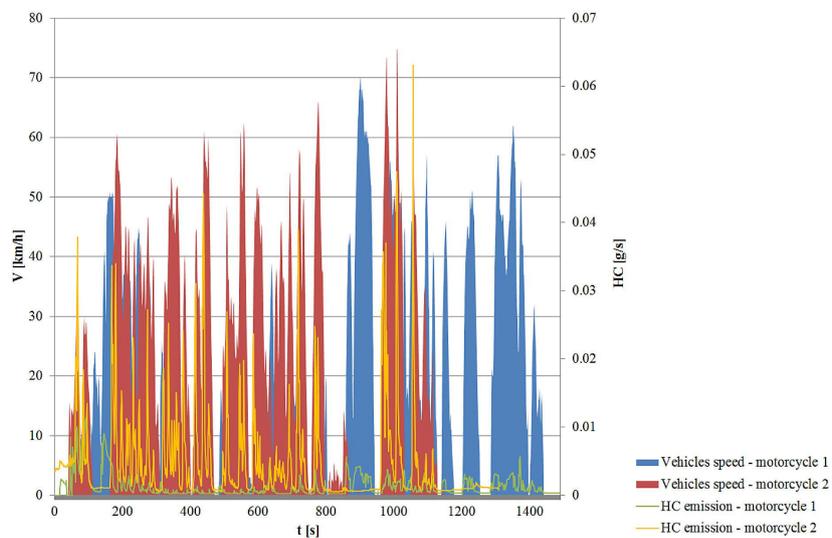


Fig. 9. The HC emission characteristics and vehicle speed presented in time

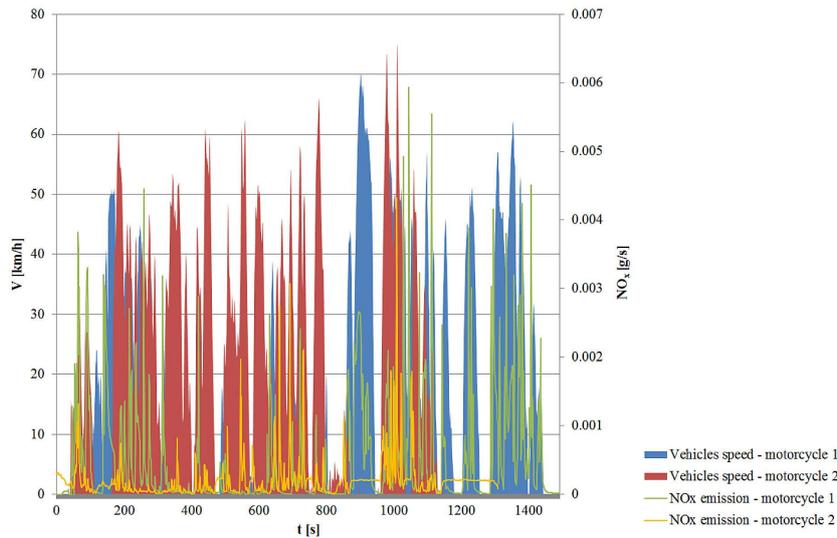


Fig. 10. The NO_x emission characteristics and vehicle speed presented in time

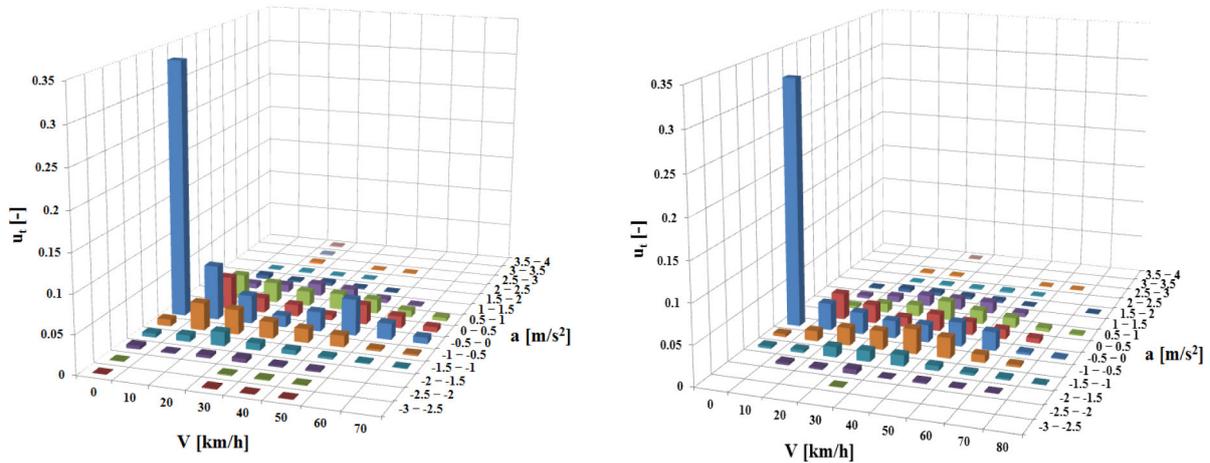


Fig. 11. Time density characteristics of a two-wheeled vehicle a) motorcycle with a displacement of 125 cm³ b) motorcycle with a displacement of 900 cm³

In the case of the smaller motorcycle, a significant share of operating time was also observed for the speed interval (0–20 km/h) and acceleration (-1–0.5 m/s²) which in total amounted to 21%. This is confirmed by the average vehicle speed, which was 17.4 km/h. While analyzing the density characteristics for the larger motorcycle and the same speed and acceleration intervals, the share of operating time was 14% of the entire test duration. In addition, both vehicle engines also worked for a long time in the interval of high vehicle speeds between 30–50 km/h and low accelerations in the interval (-1–1 m/s²), in which the total operating time share in both cases was 19%.

The recorded measurement data obtained during the tests enabled the analysis of emission ratios of the motorcycles depending on their operational parameters, which included all toxic

compounds limited by the EURO 4 norm (carbon monoxide, hydrocarbons, nitrogen oxides) as well as the non-limited carbon dioxide.

The carbon dioxide exhaust emission values were recorded in the entire speed range of test vehicles (Fig. 12). For the lower power motorcycle, the highest value was recorded for the interval of high accelerations of (1–1.5 m/s²) and speed (50–60 km/h), and it amounted to 1.986 g/s. In the case of the second test vehicle, the local maximum was also recorded in the data interval of high speeds in the range (60–70 km/h) and average accelerations of (0.5–1 m/s²), and its value was 3.83 g/s. The mean emission values of this compound obtained during the tests were 0.23 g/s for the lower power motorcycle and 1.4 g/s for the higher power vehicle.

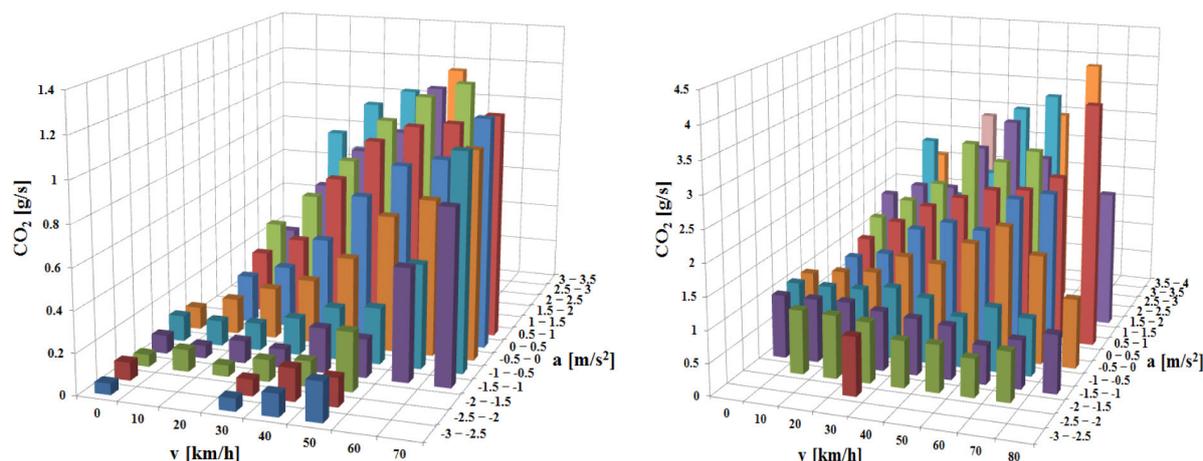


Fig. 12. CO₂ exhaust emission in speed and acceleration intervals a) motorcycle with engine displacement of 125 cm³ b) motorcycle with engine displacement of 900 cm³

The analysis of characteristics pertaining to the carbon monoxide exhaust emission intensity reveals that while its values were recorded for the entire range of engine rotational speeds, its distribution was not as uniform as in the case of carbon dioxide emissions (Fig. 13). Clear peaks in values can be observed, which in the case of the first motorcycle were found in the interval of high vehicle speeds in the range (40–50 km/h) and accelerations in the interval of (1.5–2 m/s²), and amounted to 0.146 g/s. For the other motorcycle with a displacement of 900 cm³, the highest carbon monoxide emissions were recorded at high vehicle speeds and accelerations, in the intervals (60–70 km/h) and (2.5–3 m/s²). As mentioned previously, such high vehicle speed values were the result of the temporary changes in the terrain elevation. The conditions for local maxima (high speeds, high doses of fuel supplied) are a favorable

environment for this compound to form, which is caused by local and global oxygen deficiencies. These emission values are also affected by locally high temperatures causing thermal dissociation of carbon dioxide. The mean values of carbon monoxide emissions were 0.0052 g/s and 0.015 g/s, for the two vehicles, respectively.

The hydrocarbon exhaust emission intensity values, same as in the case of previous harmful compounds, were also dependent on the vehicle operating parameters (Fig. 14). The highest emission values of this compound were recorded for high vehicle speeds and accelerations in the intervals (40–50 km/h) and (1.5–2 m/s²) for a motorcycle with engine displacement of 125 cm³, and its value was 0.005 g/s. For the more powerful two-wheeled vehicle, this value amounted to 0.047 g/s and was found in two intervals of high speeds and accelerations which were (60–70 km/h)

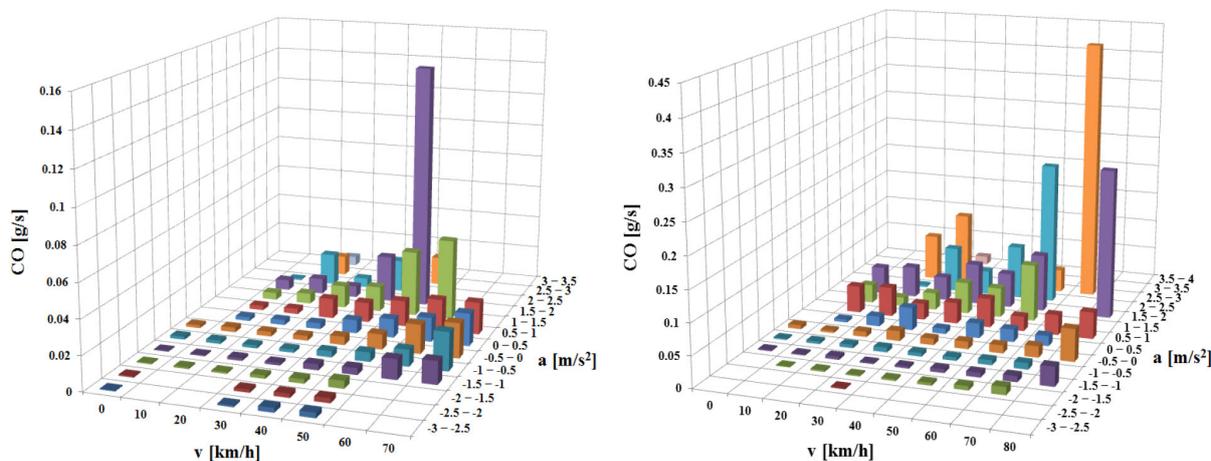


Fig. 13. CO exhaust emission in speed and acceleration intervals a) motorcycle with engine displacement of 125cm³ b) motorcycle with engine displacement of 900 cm³

and (3–3.5 m/s²) as well as (70–80 km/h) and (1.2–2 m/s²). For high vehicle speed, the injected fuel dose did not mix thoroughly, which led to incomplete combustion. The distribution of hydrocarbon emission values for the first drive is more uniform compared to the distribution obtained during the second drive of the more motorcycle with the more powerful engine. The mean values obtained in the tests were 0.0013 g/s and 0.005 g/s, respectively.

The last analyzed toxic exhaust compound was NO_x. The highest values were found in the interval of high vehicle accelerations (Fig. 14). The maximum emission value for the first vehicle was recorded for vehicle speeds in the interval (30–40 km/h) and accelerations in the interval (2–2.5 m/s²), and reached the value of 0.0039 g/s. The local maximum for the second test vehicle was 0.0043 g/s, and this value was recorded for vehicle speeds in the interval (60–70 km/h) and

accelerations in the interval (2.5–3 m/s²). High acceleration of the vehicle generates a higher temperature in the engine cylinder, which directly promotes the formation of nitrogen oxides. The average NO_x exhaust emission values for both test drives were 0.0052 g/s and 0.00021 g/s for motorcycles with a 125 cm³ and 900 cm³ displacement engines, respectively.

The road emission values of all the measured compounds restricted under the EURO 4 norm were compared to their respective limit values in the said standard. For the motorcycle with a larger engine displacement value, 133% and 116% exceedances of carbon monoxide and hydrocarbon emissions were recorded (Fig. 15). For the motorcycle with lower power, a 57% exceedance was recorded for nitrogen oxides, which is associated with higher engine loads as a result of driving with lower maximum power.

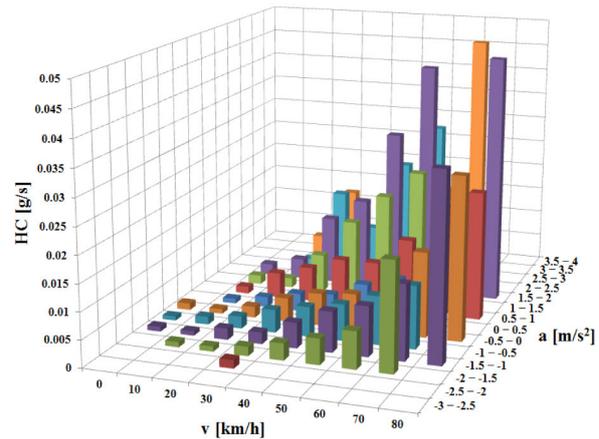
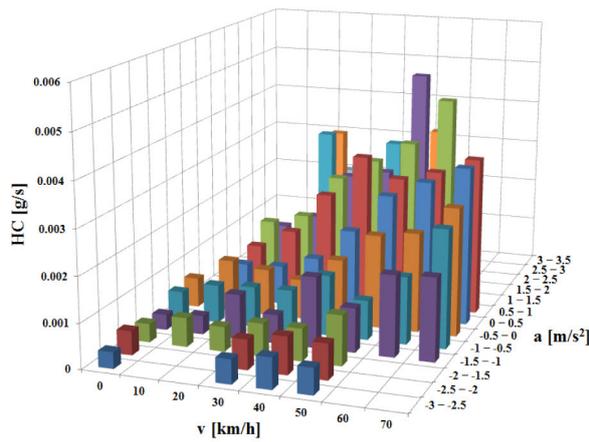


Fig. 14. HC exhaust emission in speed and acceleration intervals a) motorcycle with engine displacement of 125 cm³ b) motorcycle with engine displacement of 900 cm³

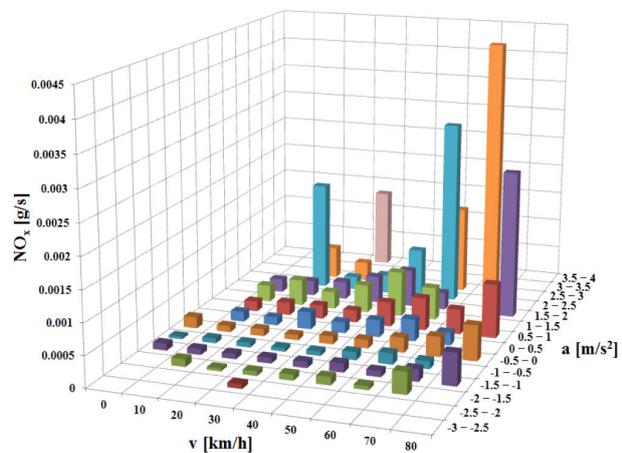
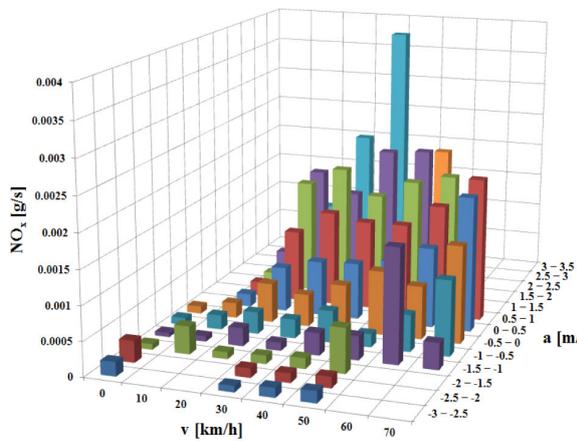


Fig. 15. NO_x exhaust emission in speed and acceleration intervals a) motorcycle with engine displacement of 125 cm³ b) motorcycle with engine displacement of 900 cm³

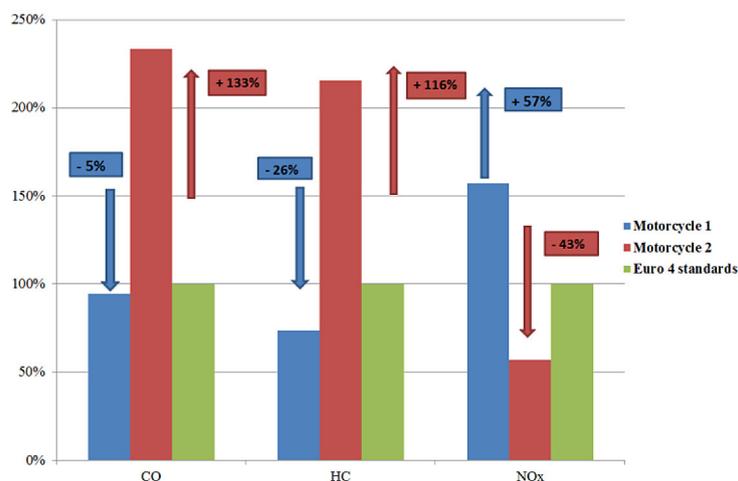


Figure 16. Comparison of the obtained road emission results with the EURO 4 norm

This phenomenon is the result of more diverse operating conditions of the engine under operating conditions than is the case with the type-approval test limited in terms of engine load range. Performing tests under actual operating conditions means that the engine load characteristics constituted a realistic representation of transient engine states, not just a dynamometer engine load curve, as it was in the case of a laboratory test. The results prove the need to introduce the RDE methodology into exhaust emissions testing for two-wheeled vehicles and tightening the regulations, as their emission drastically deviates from the accepted standards.

CONCLUSIONS

The emission norms for two-wheelers are updated less frequently than their car counterparts. Thus, any changes that take place are more severe for their manufacturers as well as end users, and each of them requires the use of new, increasingly advanced technologies, which includes both modern mechanical and electronic solutions. They also force the implementation of new emission tests, and the existing ones are characterized by increasingly higher accuracy and similarity to the actual operating conditions of vehicles. However, the results of the test carried out on two two-wheeled units with engines of different maximum power and displacement values showed that the changes in regulations are indeed necessary. The exhaust emission values obtained under actual conditions differ from the limit values. For each of the vehicles, the emission limits were exceeded for a minimum of one toxic exhaust compound.

The emergence of new research opportunities in the form of small-scale and lightweight measuring equipment facilitates testing two-wheeled vehicles under actual operating conditions. Such conditions give the most reliable and complete results on the operational parameters and the intensity of exhaust emissions from motor vehicles. These studies are intended to be used by the authors to propose an RDE testing methodology for two-wheeled vehicles in further work. The consequences of research and the methodology created (reduction of limits or design solutions to reduce the exhaust emission values) will directly affect both comfort and human health, especially in the case of residents of large urban agglomerations who are especially exposed to air pollution.

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